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Here we define the classical Lie algebras. Their root systems are given by the classical root systems A_n , B_n , C_n , and D_n . In the following E_{ij} denotes the matrix with 1 at the intersection of the *i*-th row and the *j*-th column and 0 everywhere else. The Lie bracket of E_{ij} and E_{kl} is given by

(1) $[E_{ij}, E_{kl}] = \delta_{jk} E_{il} - \delta_{il} E_{kj}.$

A_n — the special linear Lie algebras $\mathfrak{sl}_{n+1}\mathbb{C}$

$$\mathfrak{sl}_{n+1}\mathbb{C} = \{X \in \mathfrak{gl}_{n+1}\mathbb{C} \mid \text{trace } X = 0\}.$$
 Its Killing form B and Cartan subalgebra \mathfrak{h} are given by

$$\mathfrak{h} := \text{ diagonal matrices in } \mathfrak{sl}_{n+1}\mathbb{C}$$

$$= \text{ span}(E_{ii} - E_{jj}|i = 1, \dots n\}$$

$$B(x, y) = 2(n+1)\text{trace } (x \circ y)$$

Lets denote by ϵ_i , i = 1, ..., n + 1 the linear form on the diagonal matrices which assigns to a diagonal matrix its *i*'th entry. By (1) one calculates that the roots of $\mathfrak{sl}(n+1,\mathbb{C})$ are given by:

 $\Delta := \{\epsilon_i - \epsilon_j \mid 1 \le i < j \le n+1\}$

with the roots spaces $\mathbb{C} \cdot E_{ij}$. Calculating the dual and normalized dual vectors we get

$$h_{\epsilon_i - \epsilon_j} = \frac{1}{2(n+1)} (E_{ii} - E_{jj})$$
$$H_{\epsilon_i - \epsilon_j} = E_{ii} - E_{jj}$$

Hence, the root system of $\mathfrak{sl}_{n+1}\mathbb{C}$ is given by

$$\begin{split} \mathfrak{h}_0^* &= \operatorname{span}_{\mathbb{R}}(\Delta) \\ \langle \epsilon_i - \epsilon_j, \epsilon_k - \epsilon_l \rangle &= B(h_{\epsilon_i - \epsilon_j}, h_{\epsilon_k - \epsilon_l}) = \frac{1}{2(n+1)} \left(\delta_{ik} + \delta_{jl} - \delta_{il} - \delta_{jk} \right) \end{split}$$

This root system is equivalent to A_n .

B_n — the odd-dimensional orthogonal Lie algebras $\mathfrak{so}_{2n+1}\mathbb{C}$

 $\mathfrak{so}_{2n+1}\mathbb{C} = \{X \in \mathfrak{gl}_{2n+1}\mathbb{C} \mid X + X^t = 0\}$. Set $D_{ij} := E_{ij} - E_{ji}$ for $1 \le i \ne j \le 2n+1$. Then $(D_{ij}|1 \le i < j \le 2n+1)$ is a basis of $\mathfrak{so}_{2n+1}\mathbb{C}$. Then

(2)
$$[D_{ij}, D_{kl}] = \delta_{jk} D_{il} + \delta_{il} D_{jk} - \delta_{jl} D_{ik} - \delta_{ik} D_{jl}$$

The Killing form is given by

$$B(x,y) = (2n-1)$$
trace $(x \circ y)$.

Consider now the following basis of $\mathfrak{so}_{2n+1}\mathbb{C}$:

$$\begin{array}{rcl} H_i &:= & \sqrt{-1}D_{2i-1 \ 2i} \ , & i=1,\dots n \\ K_i^{\pm} &:= & D_{2i-1 \ 2n+1} \pm \sqrt{-1}D_{2i \ 2n+1} \ , & i=1,\dots n \\ L_{ij}^{\pm} &:= & (D_{2i-1 \ 2j-1} - D_{2i \ 2j}) & \pm & \sqrt{-1}(D_{2i-1 \ 2j} + D_{2i \ 2j-1}) \ , & 1 \le i < j \le n \\ M_{ij}^{\pm} &:= & (D_{2i-1 \ 2j} - D_{2i \ 2j-1}) & \pm & \sqrt{-1}(D_{2i-1 \ 2j-1} + D_{2i \ 2j}) \ , & 1 \le i < j \le n. \end{array}$$

Then the H_i 's span a Cartan subalgebra \mathfrak{h} . Lets denote by η_i , $i = 1, \ldots, n$, the linear form on the Cartan subalgebra \mathfrak{h} given by $\eta_k(H_i) = -\delta_{ik}$. A direct calculation using (2) gives that the roots of $\mathfrak{so}(2n+1,\mathbb{C})$ are given by:

$$\Delta := \{ \pm \eta_i \}_{i=1}^n \cup \{ \pm (\eta_i + \eta_j) \}_{1 \le i < j \le n} \cup \{ \pm (\eta_i - \eta_j) \}_{1 \le i < j \le n}$$

with the root spaces: $\mathbb{C} \cdot K_i^{\pm}$, $\mathbb{C} \cdot L_{ij}^{\pm}$, $\mathbb{C} \cdot M_{ij}^{\pm}$

This root system is equivalent to B_n .

C_n — the symplectic Lie algebras $\mathfrak{sp}_n\mathbb{C}$

 $\mathfrak{sp}_n \mathbb{C} = \{ X \in \mathfrak{gl}_{2n} \mathbb{C} \mid X^t J_n + J_n X = 0 \} \text{ with } J_n \stackrel{\text{def}}{=} \begin{pmatrix} 0 & \mathbf{1}_n \\ -\mathbf{1}_n & 0 \end{pmatrix}, \text{ where } \mathbf{1}_n \text{ is the } n \times n \text{ identity matrix.}$ This Lie algebra has the Killing form

 $B(x,y) = 2(n+1) \text{trace } (x \circ y).$

A simple calculation shows that

$$\mathfrak{sp}_n \mathbb{C} = \left\{ \left(\begin{array}{cc} A & B \\ C & -A^t \end{array} \right) \in \mathfrak{gl}_{2n} \mathbb{C} \mid B^t = B \text{ and } C^t = C \right\}$$

and a Cartan subalgebra is given by the diagonal matrices in $\mathfrak{sp}_n\mathbb{C}$,

 $\mathfrak{h} \ = \ \mathrm{span} \left(E_{ii} - E_{i+n \ i+n} \ | \ 1 \leq i \leq n \right).$

The roots spaces are spanned by the following matrices

$$\begin{array}{rcl} Q_{ij} & := & E_{ij} - E_{i+n \ j+n}, \ 1 \le i \ne j \le n \\ P_{ij}^+ & := & E_{i \ j+n} + E_{j \ i+n}, \ 1 \le i \le j \le n \\ P_{ij}^- & := & P_{ij}^t & = & E_{j+n \ i} + E_{i+n \ j}, \ 1 \le i \le j \le n \end{array}$$

The roots are given by

$$\Delta := \{\pm 2\epsilon_i\}_{i=1}^n \cup \{\pm (\epsilon_i + \epsilon_j)\}_{1 \le i < j \le n} \cup \{\epsilon_i - \epsilon_j\}_{1 \le i, j \le n}$$
with the root spaces: $\mathbb{C} \cdot P_{ii}^{\pm}$, $\mathbb{C} \cdot P_{ij}^{\pm}$, $\mathbb{C} \cdot Q_{ij}$

where the ϵ_i 's are defined as above. Thus the root system of the symplectic Lie algebra is isomorphic to C_n .

D_n — the even dimensional orthogonal Lie algebras $\mathfrak{so}_{2n}\mathbb{C}$

 $\mathfrak{so}_{2n}\mathbb{C} = \{X \in \mathfrak{gl}_{2n}\mathbb{C} \mid X + X^t = 0\}$. As for the other orthogonal Lie algebras the Killing form is given by B(x, y) = 2(n-1)trace $(x \circ y)$.

As above, the Cartan subalgebra is spanned by

$$H_i := \sqrt{-1}D_{2i-1 \ 2i} , \qquad i = 1, \dots n$$

and the roots of $\mathfrak{so}(2n,\mathbb{C})$ are given by:

$$\Delta := \{ \pm (\eta_i + \eta_j) \}_{1 \le i < j \le n} \cup \{ \pm (\eta_i - \eta_j) \}_{1 \le i < j \le n}$$

with the root spaces: $\mathbb{C} \cdot L_{ij}^{\pm}$, $\mathbb{C} \cdot M_{ij}^{\pm}$

I.e. the root system is equal to D_n .

	Dynkin diagram	root system	Lie algebra
(3)	•	$B_1 = C_1 = A_1$	$\mathfrak{so}_3\mathbb{C}\ \simeq\ \mathfrak{sp}_1\mathbb{C}\ \simeq\ \mathfrak{sl}_2\mathbb{C}$
		$D_2 = A_1 \cup A_1$	
	•	↓	$\mathfrak{so}_4\mathbb{C}\ \simeq\ \mathfrak{sl}_2\mathbb{C}\oplus\mathfrak{sl}_2\mathbb{C}$
		$B_2 = C_2$	$\mathfrak{so}_5\mathbb{C}\ \simeq\ \mathfrak{sp}_2\mathbb{C}$
	•	$D_{3} = A_{3}$	$\mathfrak{so}_6\mathbb{C}\ \simeq\ \mathfrak{sl}_4\mathbb{C}$

For small n there are the following **isomorphisms** between these Lie algebras, as it can be seen from the Dynkin diagrams:

Note that the orthogonal Lie algebras here are defined differently than in Chapter 12 of the book by Erdmann and Wildon, *Introduction to Lie Algebras*, Springer 2006. For us, the orthogonal Lie algebras are given as skew symmetric matrices whereas in the book they are defined in a way that they contain the diagonal matrices as maximal toral subalgebra. Of course, both Lie algebras are isomorphic and the isomorphism can be understood by a change of the basis in \mathbb{C}^n .