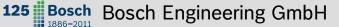
### Individual E-Mobility System Solutions for Automotive and Off-Highway Applications

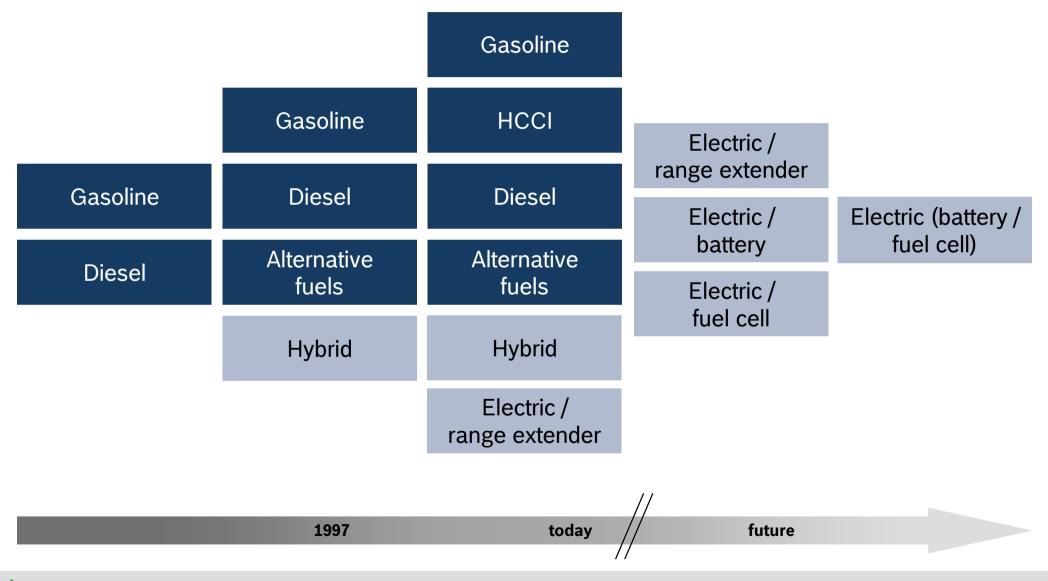


#### Dr.-Ing. Martin Lenz, Bosch Engineering GmbH





# The "Powertrain-Map"

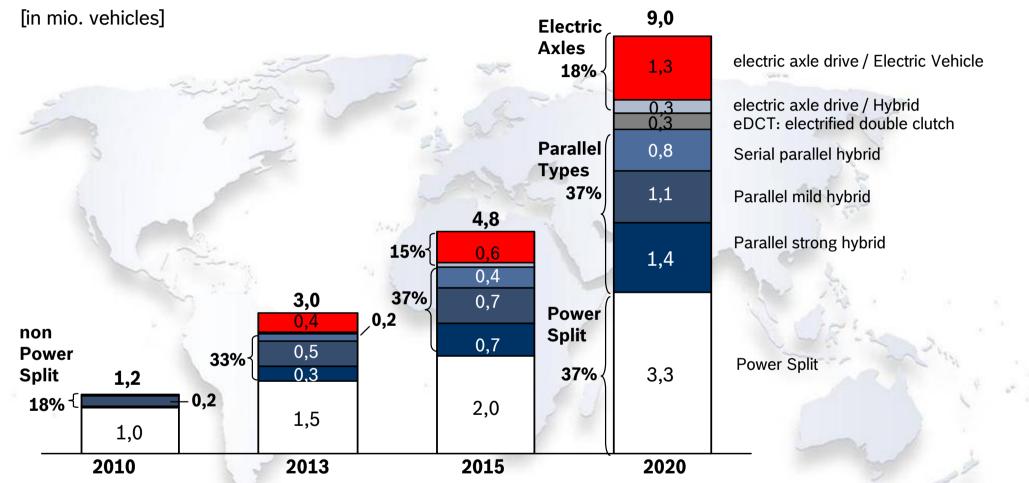


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# Market Trends: Electrification Systems



Non-Powersplit Systems gaining ground.
Parallel and Electric Axle systems w/ high shares.

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### "We provide individual E-Mobility solutions"



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# **Development areas E-mobility**

System definition and development

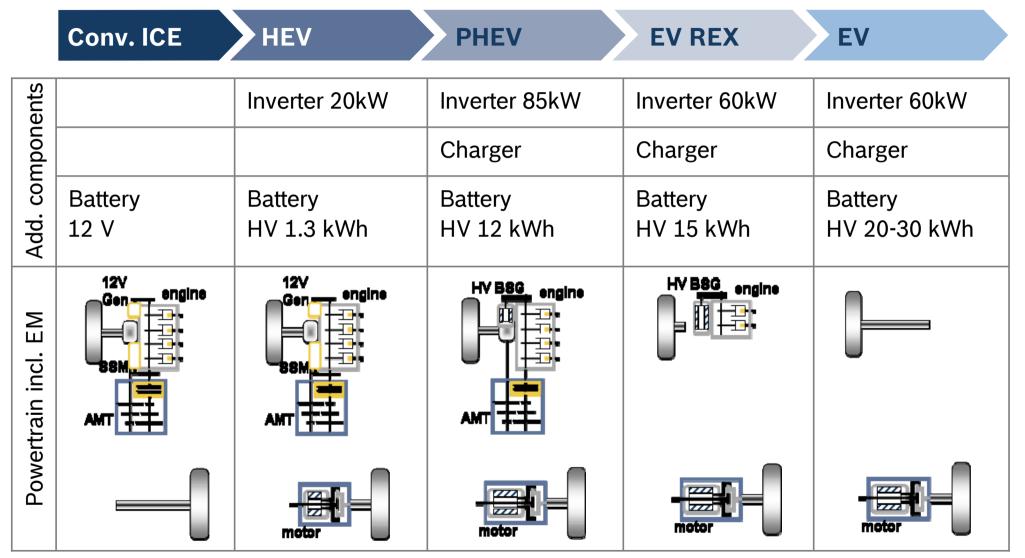
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Prototype & demonstrator construction

E/E-architecture, control units, Chassis & brake system, (CAN, Flexray), safety vehicle dynamics Engineering powertrain Infotainment, HMI, cluster **Engineering power electronics** Energy & battery management **F-Infrastructure Bosch** Bosch Engineering GmbH



### System development

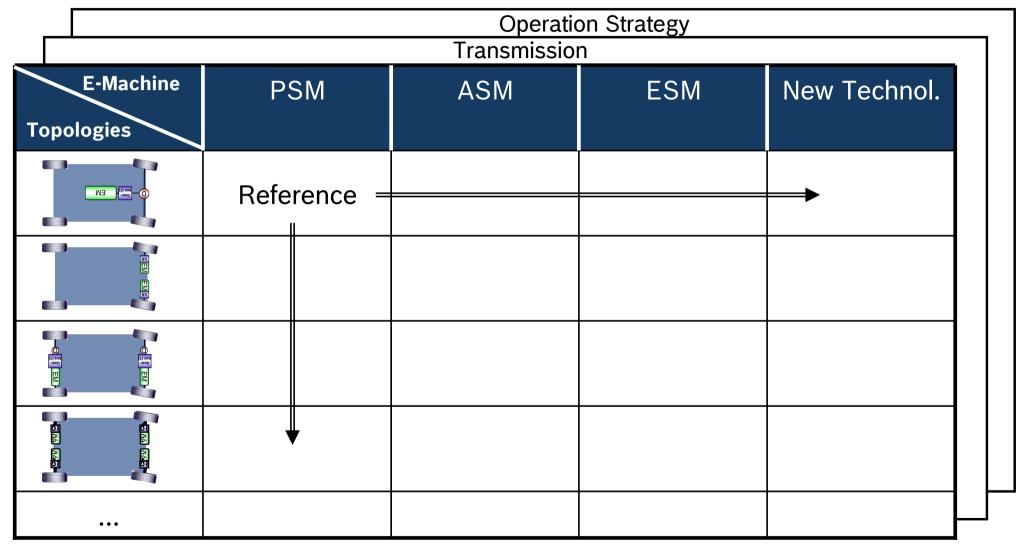




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# Powertrain Investigation expl. EV



PSM: **Bosch** Bosch Engineering GmbH ESM: Electric Induction Synchronous Machine

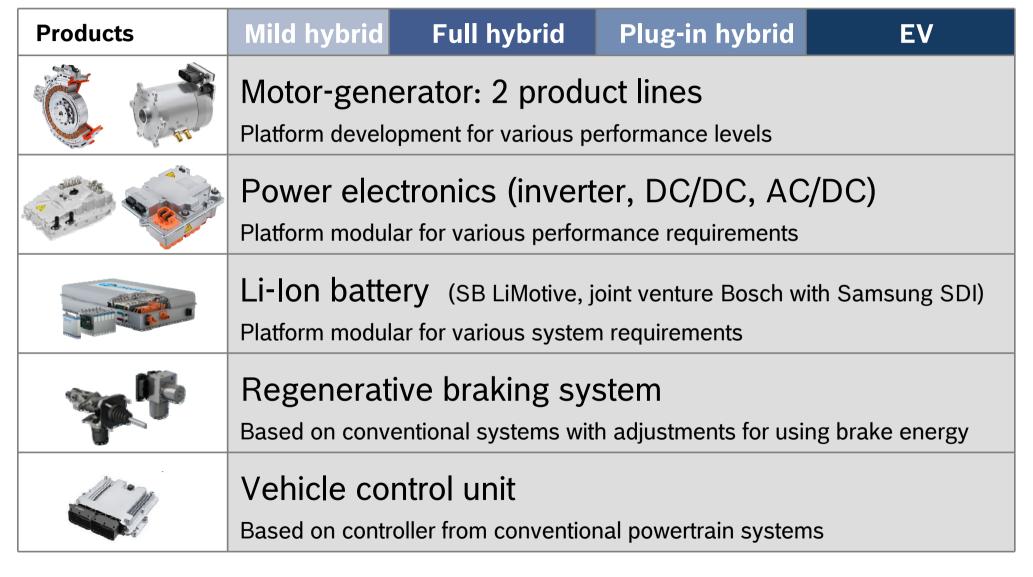
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Permanent Magnet Synchronous Machine

ASM: Asynchronous Induction Machine



# Bosch hardware portfolio

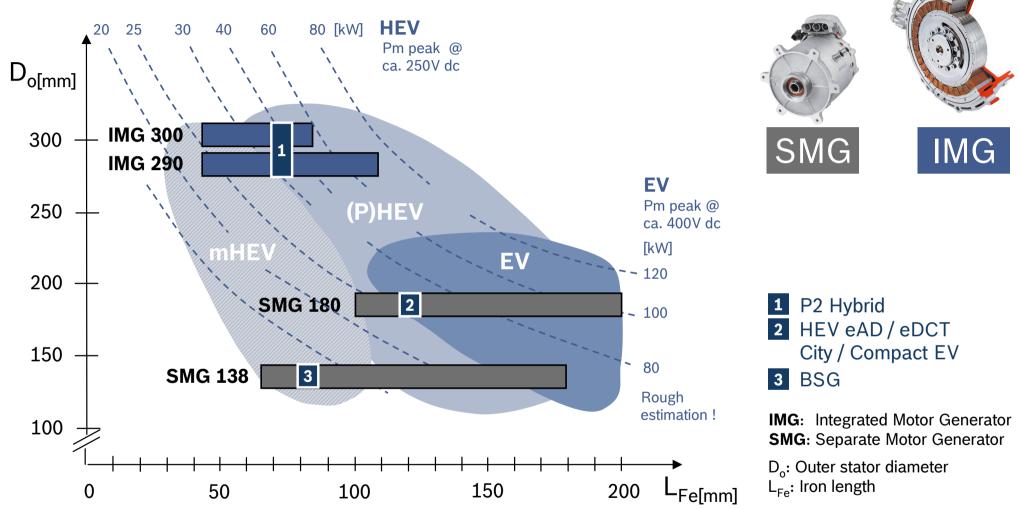


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### Electric Machine – Product Portfolio



### Bosch covers major (P)HEV / EV market requirements Flexible construction kit w/ scalable design and production line concept

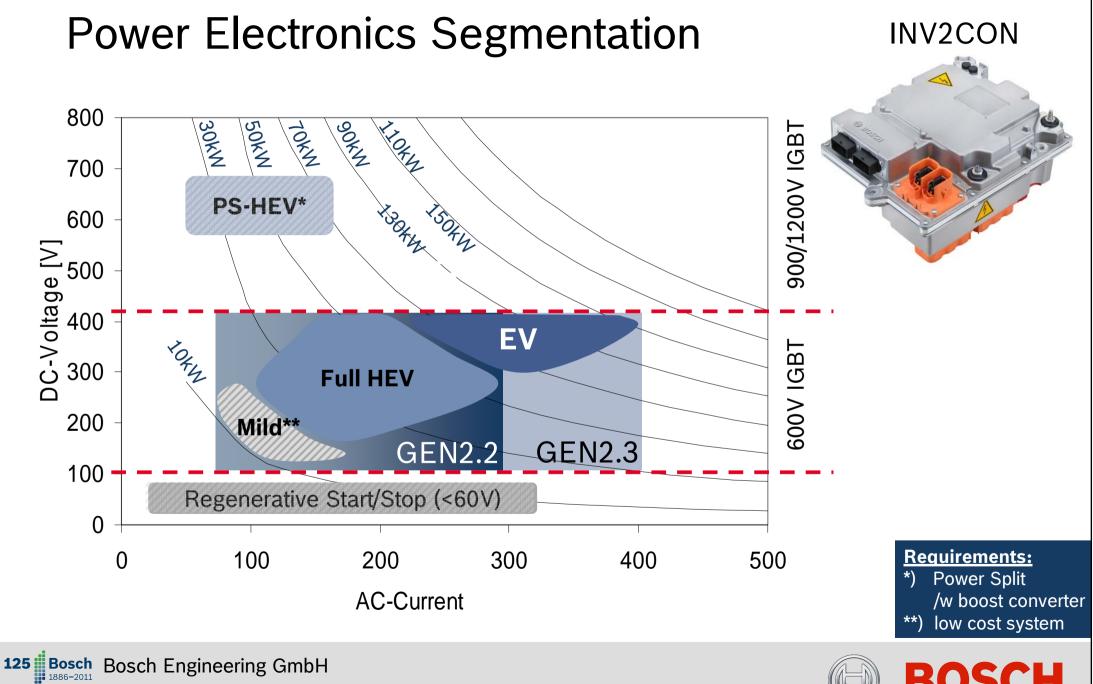
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# Bosch "e-Drive" components

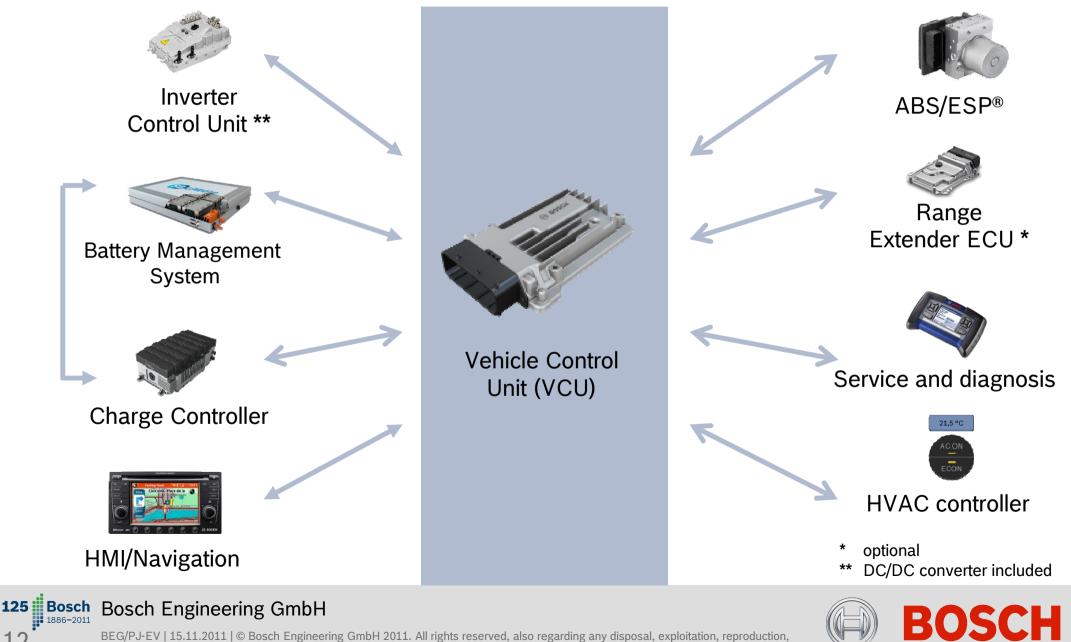
Separate Motor Generator					
Product specification					
Active diameter / lengths	180 mm / 120 mm				
Peak torque max.	up to 200 Nm [@ 400A <sub>rms</sub> ]				
Speed max.	12,500 rpm				
Mechanical power max.	40 kW (INVCON 2.2) 80 kW (INVCON 2.3)				
Total mass	28 kg				
Cooling	Water-jacket 8l/min 85°C <sub>max</sub>				





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# Vehicle control unit



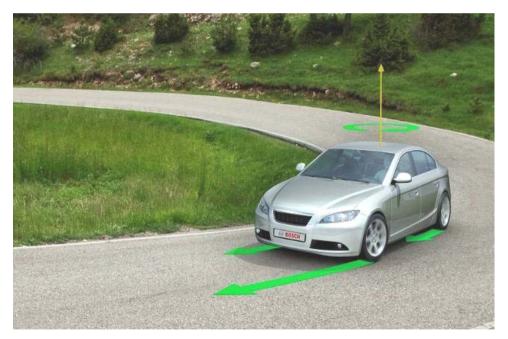
editing, distribution, as well as in the event of applications for industrial property rights.

# Chassis system solutions E-Mobility

- Brake systems
  - Component setup
  - Recuperation
  - Torque coordination

- Vehicle driving dynamics
  - Safety
  - Traction control
  - Torque vectoring





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### **Regenerative Braking Systems: Overview**

# Recommended CRBS for different HEV/EV types

Brake System	HEV		Plug-in HEV	EV
	mild	strong		
ESP® w/ RBC	<ul> <li>Combination w/ MV</li> <li>Low recuperation &lt;</li> <li>Low cost</li> </ul>			
ESP <sup>®</sup> hybrid SOP 2014*	<ul> <li>Recuperation</li> </ul>	w/ MVP or EVP a < 0,2g for x-split circu mance optimized	it	
ESP® hev SOP 2012	<ul> <li>Recuperation</li> </ul>	w/ MVP or EVP n < 0,2g for II-split circu for enhanced performa		
HAS hev SOP 2011		•	Vacuum independent Recuperation up to 0,3 High performance	3g
iBooster <i>hev</i>		•	Vacuum independent Recuperation up to 0,3 High perform., improv	Ŭ l

#### \*Target

HEV: Hybrid Electric Vehicle; PHEV: Plug-In Hybrid Electric Vehicle; EV REX: Electric Vehicle with range extender; EV: Electric Vehicle

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# Product safety and functional safety

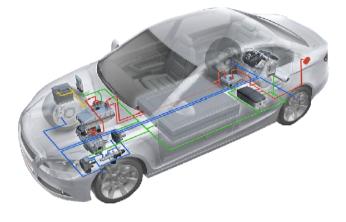
- New challenges regarding product safety and functional safety
  - Laws and regulations (e.g. ECE R100, FMVSS 305)
  - Standards (e.g. ISO 6469, ISO 26262)
  - Customer requirements (e.g. HV)











- We provide safety concepts for
  - Electric shock (e.g. U~ 400V)
  - Fire (e.g. I ~ 300A)
  - Unintended acceleration / deceleration
  - Battery hazards (battery fire, hazardous chemicals)







# Active sound enhancement interior and exterior

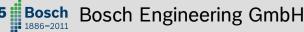
 Generation of a synthetic engine sound according to driving situation

 Driving-noise emulation for pedestrian safety in electric / hybrid vehicles





### Customer specific applications and adaptation for individual solutions

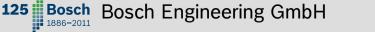




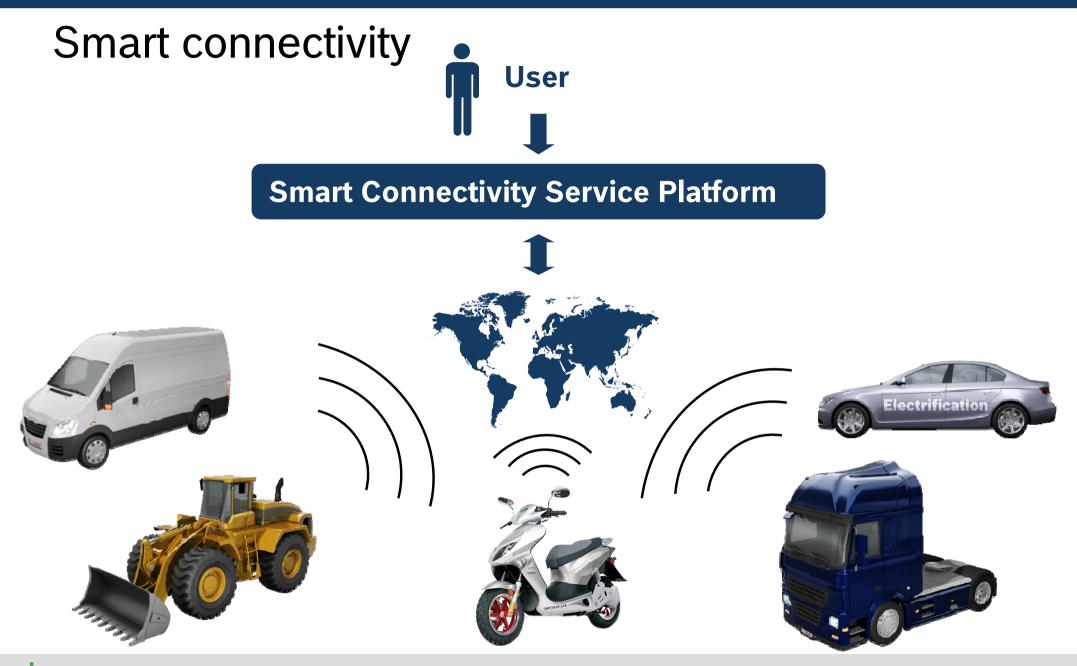
# Charging systems engineering

- In-Vehicle Solution
  - Hardware
  - Software
  - Calibration
  - Integration
- Non-Conductive Concept
  - Hardware ECU
  - Software
- Alternative Concept
  - Investigation









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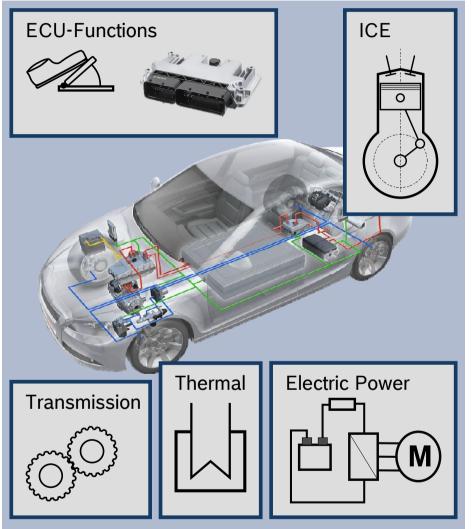
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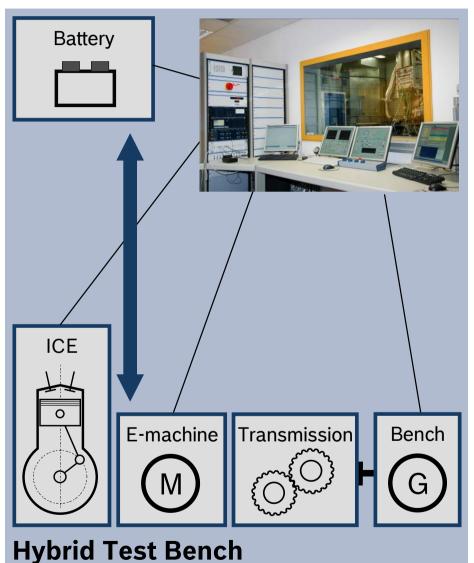
# Powertrain simulation and testing



#### **Virtual Powertrain**

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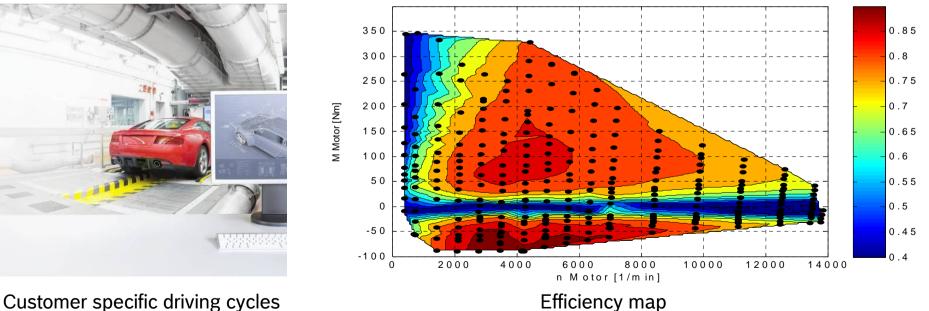
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# Test procedures for hybrid and electric vehicles

- Consumption measurement in accordance with the test procedures  $\rightarrow$ ECE-R101 or CFR40-Part96
- Determination of "real life" fuel consumption and optimization of the  $\rightarrow$ operation strategy (drive cycle, ambient temperature etc.)
- Gradient profiles to verify the robustness of the electric system ->
- Efficiency measurement for different speed-load setpoints ->



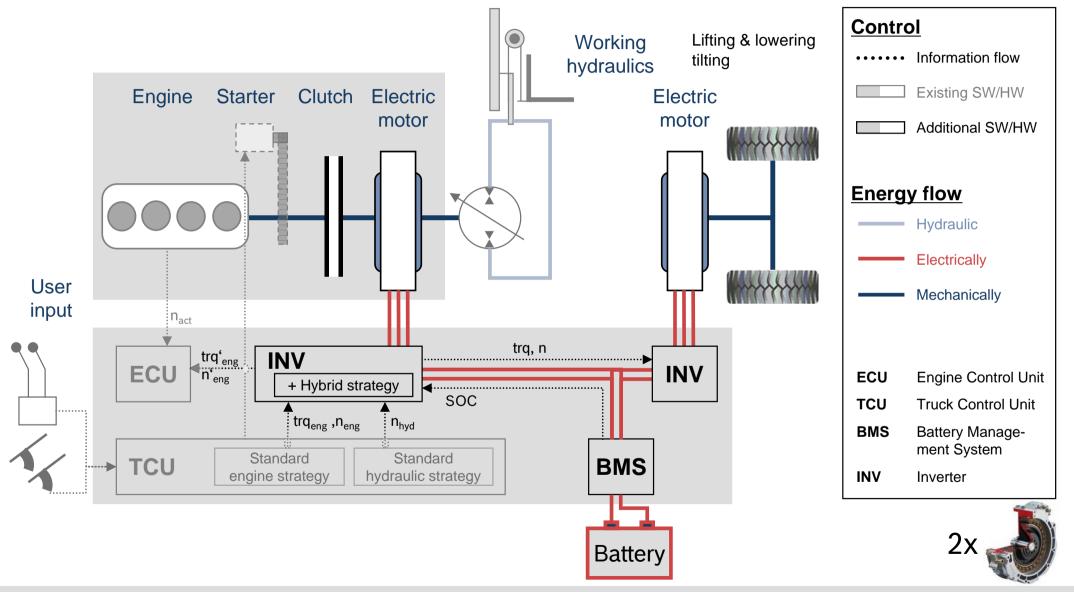
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# Electric powertrain fork lift trucks

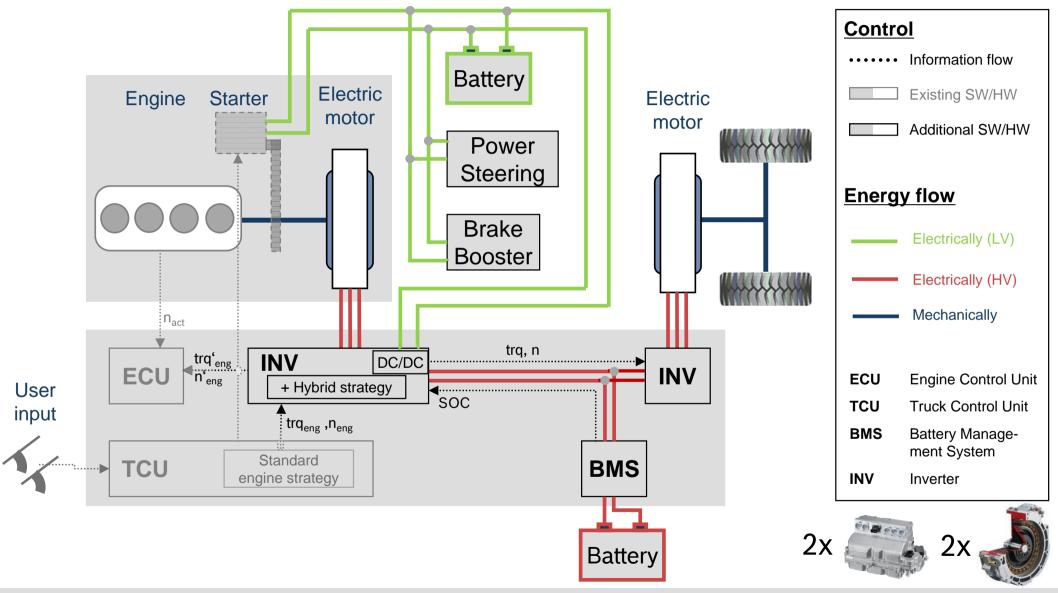


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### Electric powertrain tow truck



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# Thank you for your attention !

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